

From Array Domains to Abstract Interpretation Under Store-Buffer-Based Memory Models

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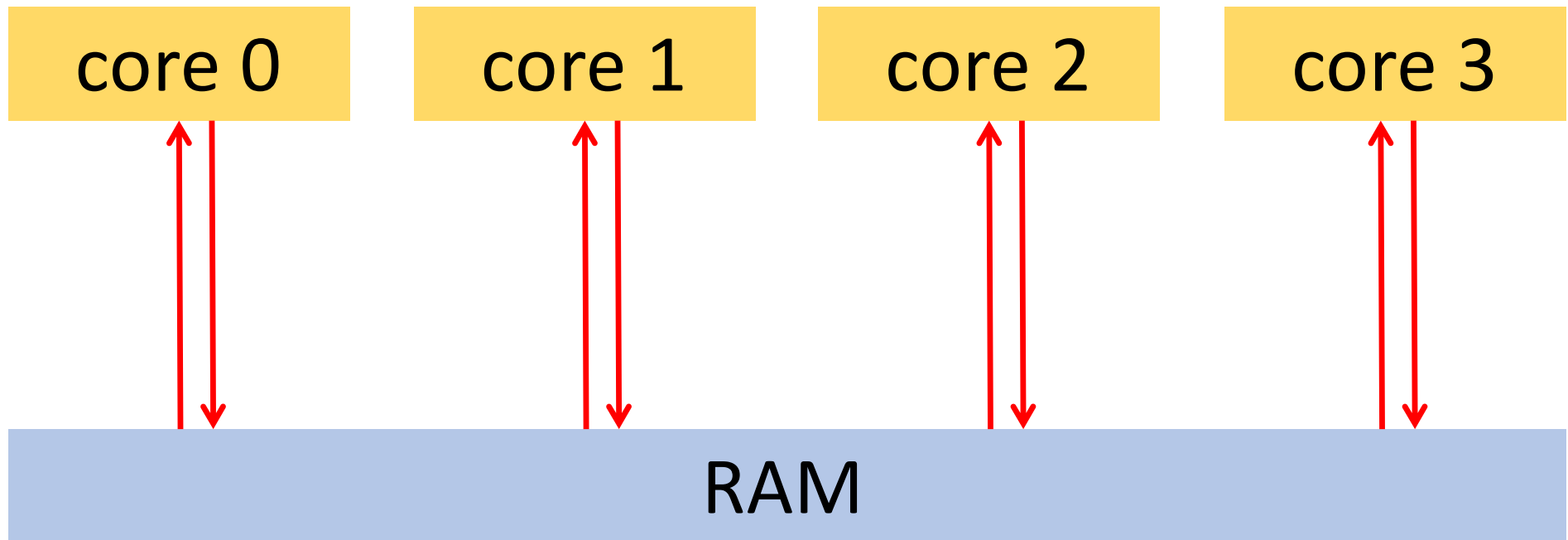
De quoi s'agit-il?

- New abstract interpretation of concurrent programs
- Setting: Weak memory consistency
- Model: store-buffer (FIFO) of infinite size

- including theoretical model, proof and working implementation (OCaml)

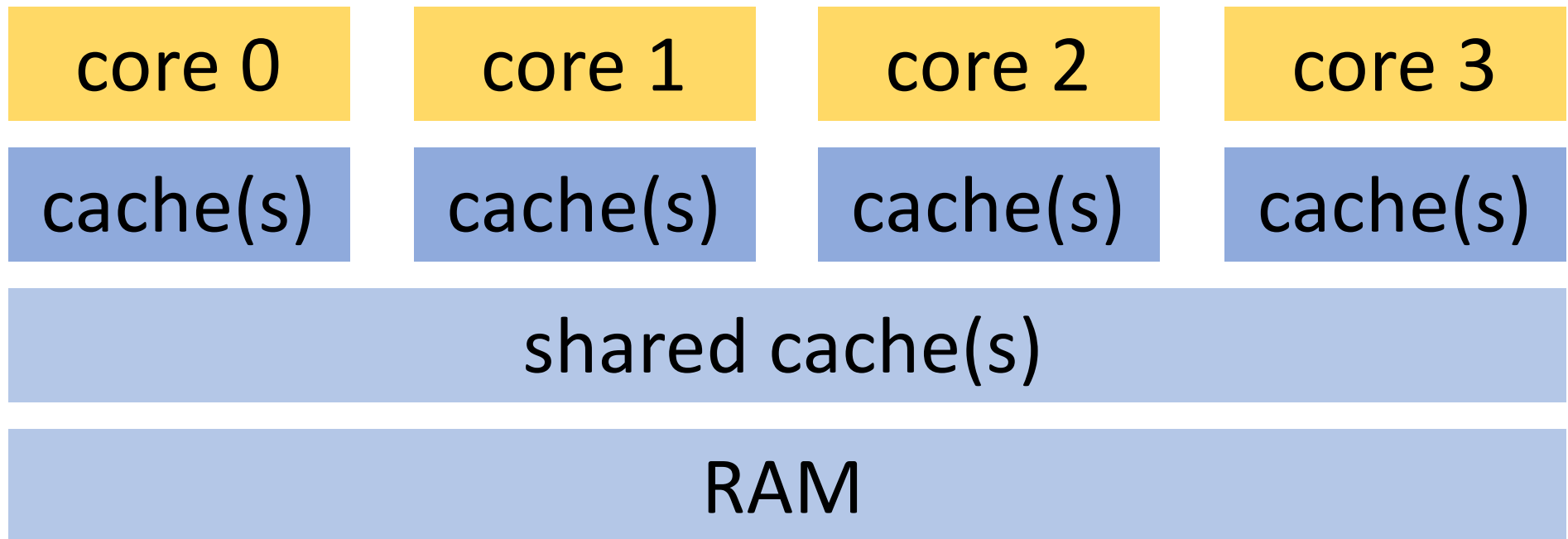
Memory models in Hardware and Languages

- **Strong consistency**



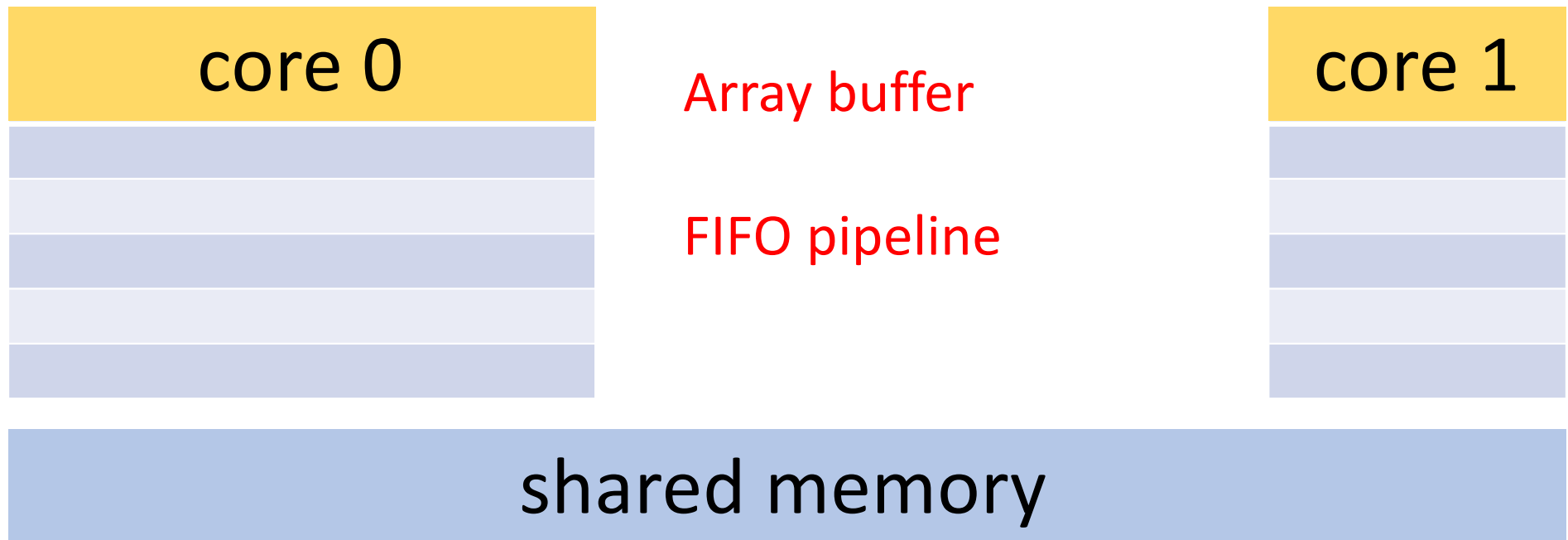
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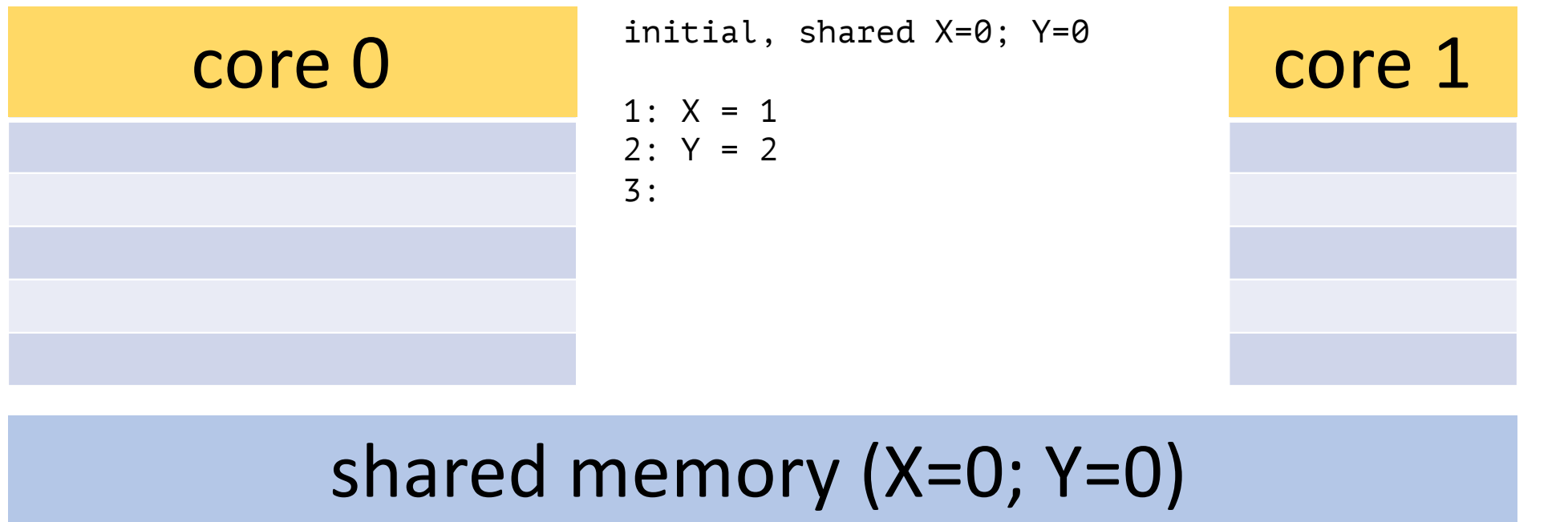
Memory models in Hardware and Languages

- Weak consistency. **TSO: total store ordering (x86)**



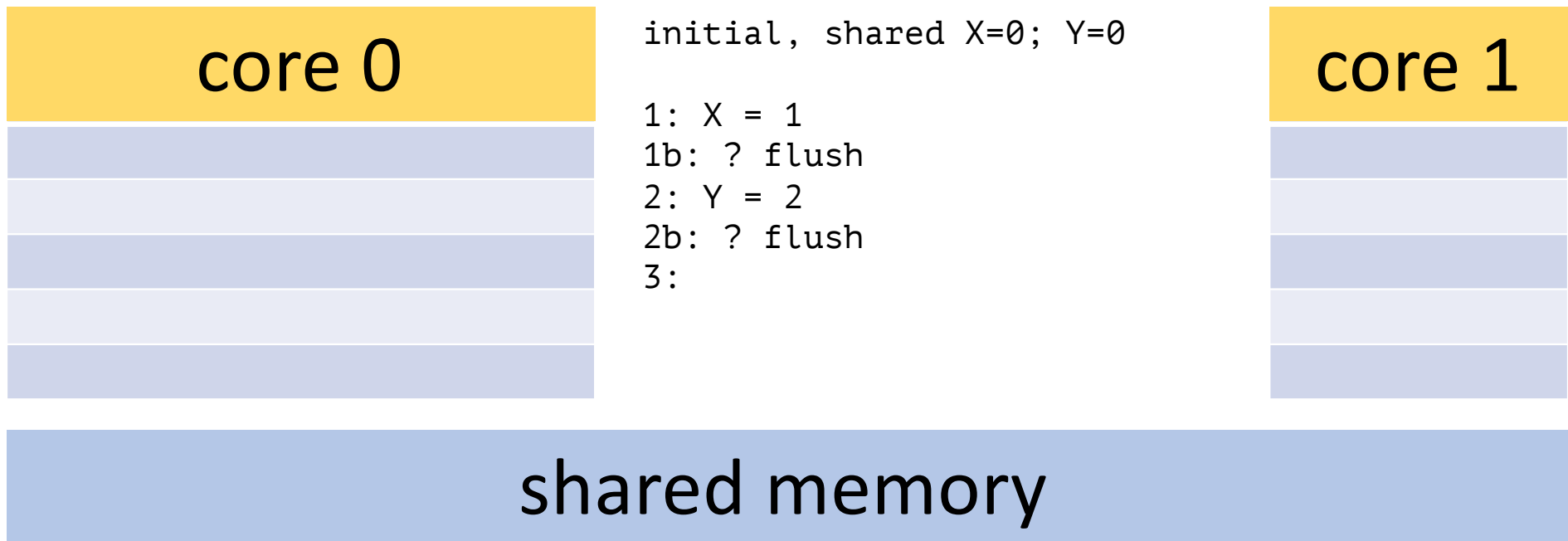
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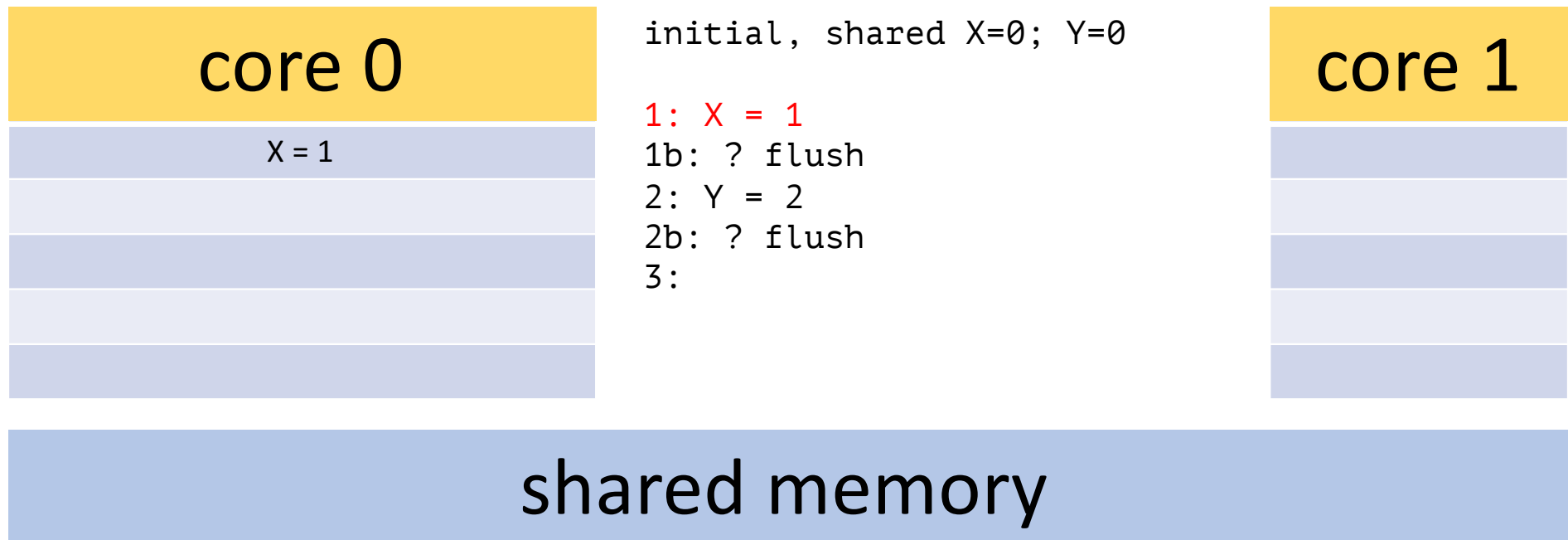
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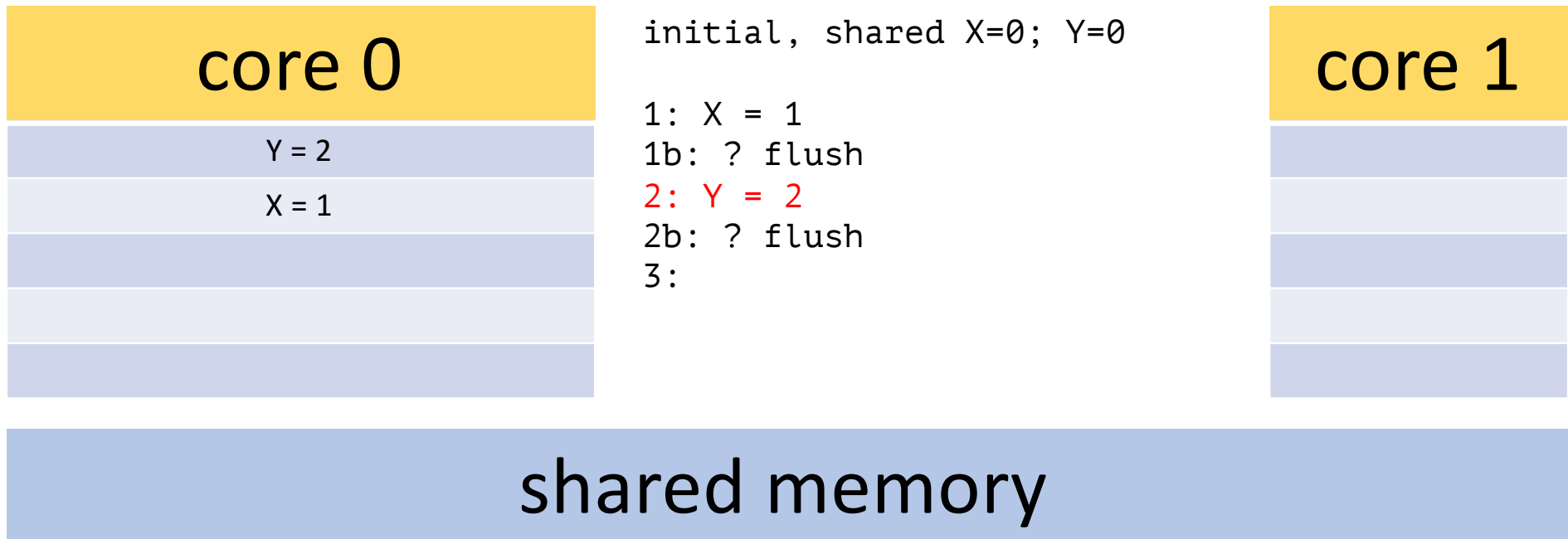
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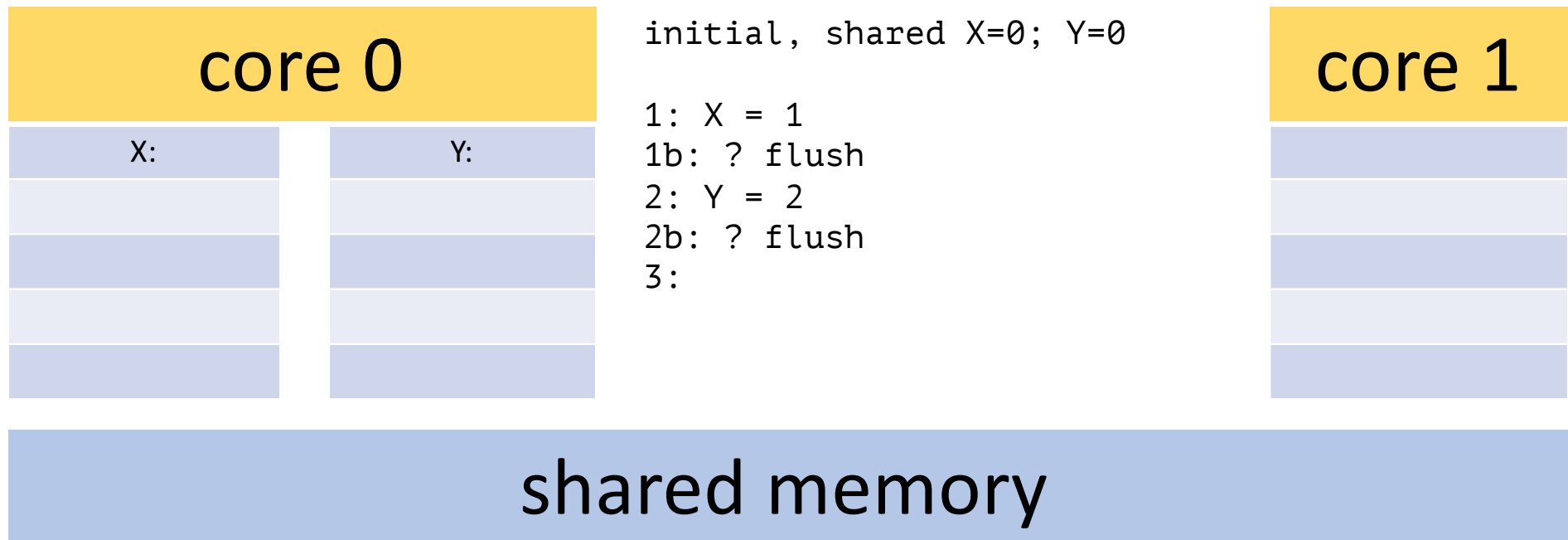
What can it see?



Memory models in Hardware and Languages

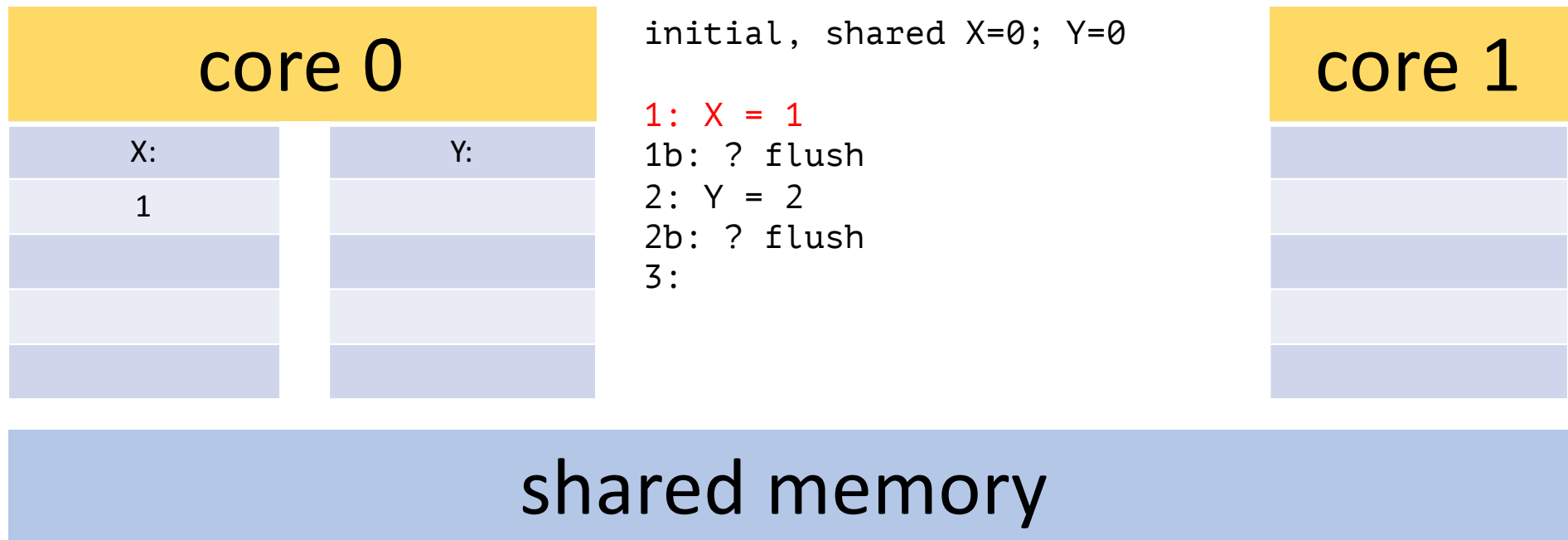
- Weak consistency. **PSO: partial store ordering (ARM)**

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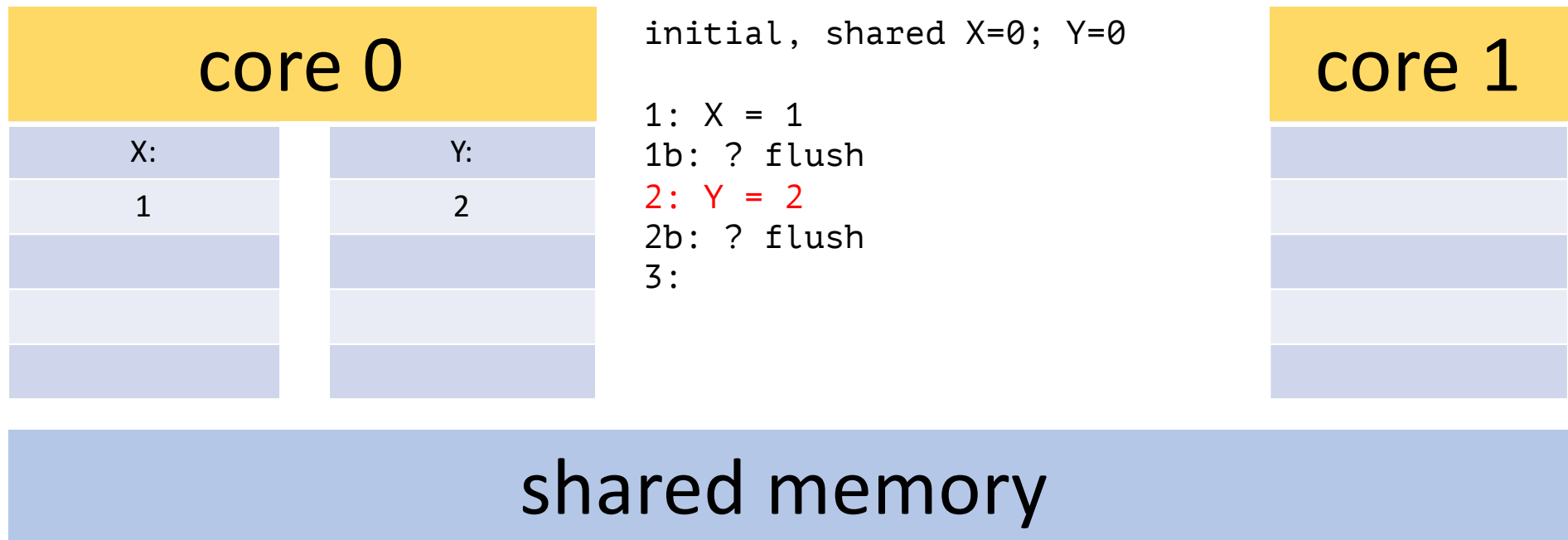
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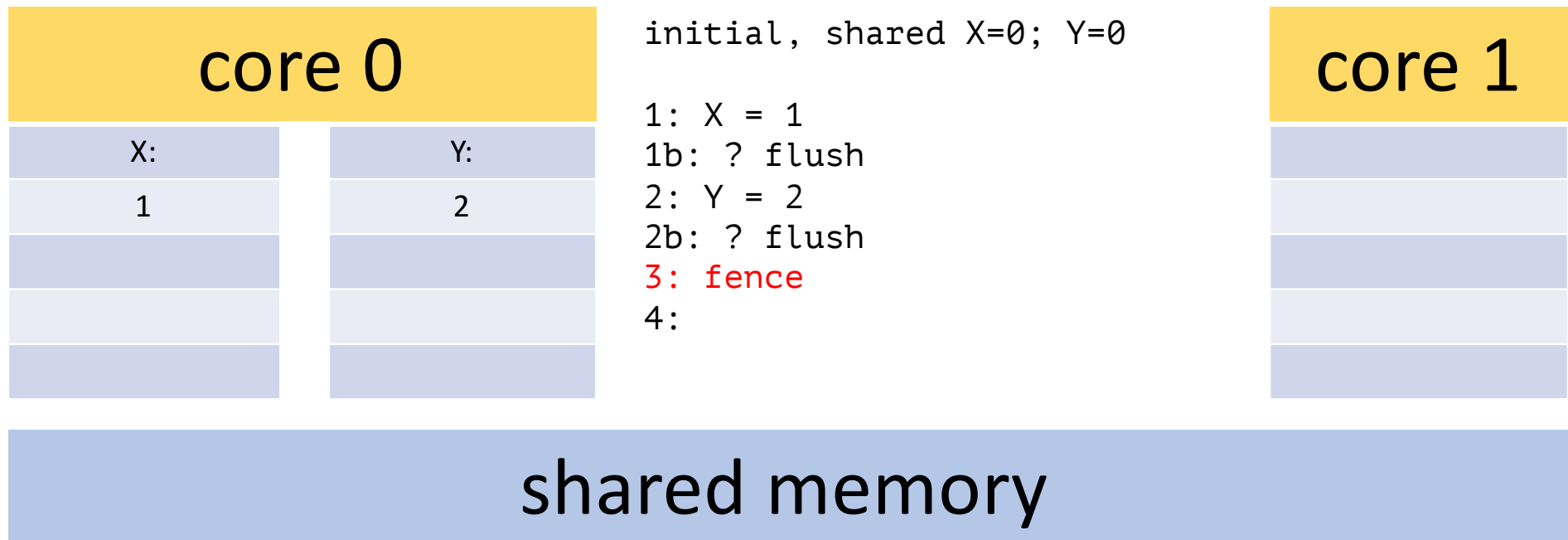
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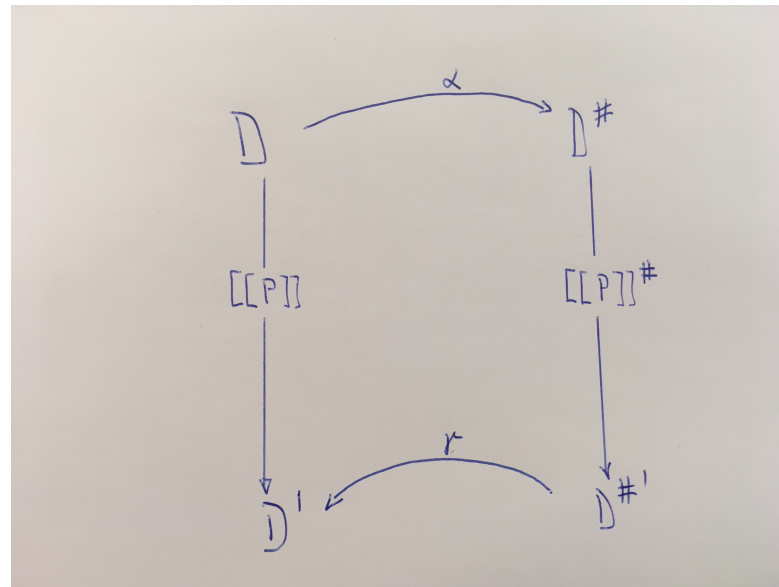


Verification: Model checkers

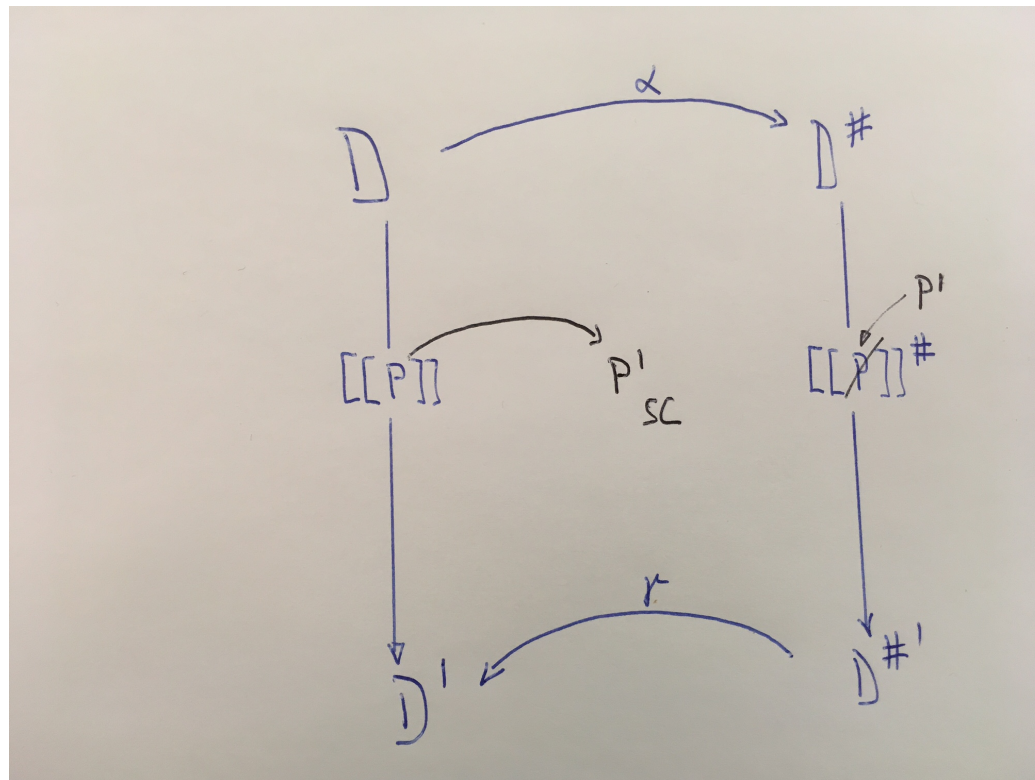
- Promela / spin
- Scyther: crypto protocols

- Limitation: only finite state space
- State space explosion

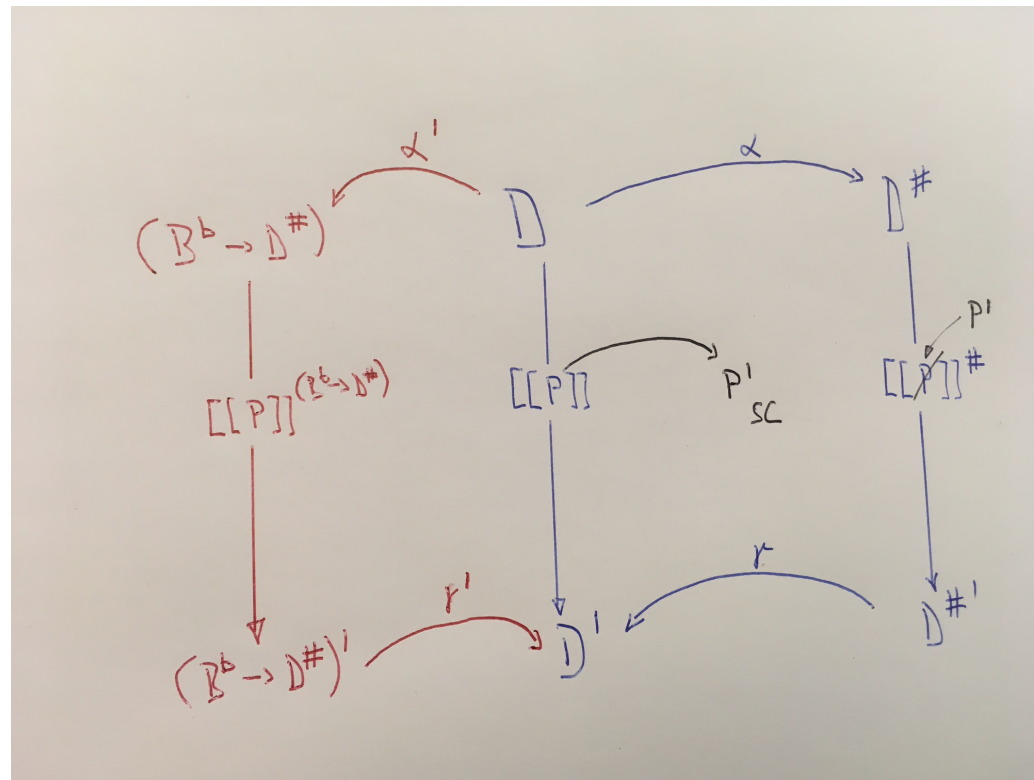
Verification: Abstract interpretation. SC



Verification: Abstract interpretation. Dan et al.



Verification: Abstract interpretation. This study



Comparison

	buffer size		
		n	∞
state size	m	Model Checker	-----
	∞	Dan et al.	This study

PSO model: concrete domain \mathcal{D}

$N > 0$

thread 1		thread 2	
x_1^1	y_1^1	x_1^2	z_1^2
x_2^1	y_2^1	x_2^2	z_2^2
x_3^1	y_3^1		z_3^2
x_4^1			
x_5^1			

shared: $x^{\text{mem}}, y^{\text{mem}}, z^{\text{mem}}$

$$\text{VarMem} \triangleq \{x^{\text{mem}} \mid x \in \text{Var}\} \quad (1)$$

$$\text{Mem} \triangleq \text{VarMem} \rightarrow \mathbb{V} \quad \text{Reg} \triangleq \text{VarReg} \rightarrow \mathbb{V} \quad (2)$$

$$\forall x \in \text{Var}, T \in \text{Thread}, N \in \mathbb{N}, \text{VarBuf}(x, T, N) \triangleq \{x_i^T \mid 1 \leq i \leq N\} \quad (3)$$

$$\text{Buf}(x, T, N) \triangleq \text{VarBuf}(x, T, N) \rightarrow \mathbb{V} \quad (4)$$

$$\text{BufSizes} \triangleq (\text{Var} \times \text{Thread}) \rightarrow \mathbb{N} \quad (5)$$

$$\mathcal{S} \triangleq \bigcup_{N \in \text{BufSizes}} \left(\text{Mem} \times \text{Reg} \times \prod_{\substack{x \in \text{Var} \\ T \in \text{Thread}}} \text{Buf}(x, T, N(x, T)) \right) \quad (6)$$

$$\mathcal{D} \triangleq \mathcal{P}(\mathcal{S}) \quad (7)$$

Fig. 3. A concrete domain for PSO programs

PSO model: concrete domain \mathcal{D}

$N > 0$

thread 1		thread 2	
x_1^1	y_1^1	x_1^2	z_1^2
x_2^1	y_2^1	x_2^2	z_2^2
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$$\forall T \in \text{Thread}, \llbracket \cdot \rrbracket_T : \mathcal{D} \rightarrow \mathcal{D} \quad (8)$$

$$\begin{aligned} \llbracket x := e \rrbracket_T \{S\} &\triangleq \llbracket x_1^T := e \rrbracket \circ \llbracket x_2^T := x_1^T \rrbracket \circ \dots \\ &\dots \circ \llbracket x_{N_S(x,T)+1}^T := x_{N_S(x,T)}^T \rrbracket \circ \llbracket \text{add } x_{N_S(x,T)+1}^T \rrbracket \{S\} \end{aligned} \quad (9)$$

$$\llbracket r := x \rrbracket_T \{S\} \triangleq \begin{cases} \llbracket r := x^{\text{mem}} \rrbracket S & \text{if } N_S(x, T) = 0 \\ \llbracket r := x_1^T \rrbracket S & \text{if } N_S(x, T) \geq 1 \end{cases} \quad (10)$$

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x_2^1	y_2^1	x_2^2	z_2^2
x_3^1	y_3^1	x_3^2	z_3^2
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Fig. 4. Concrete semantics in PSO

Abstraction: handling ∞

- Key insight: summarize and partition.

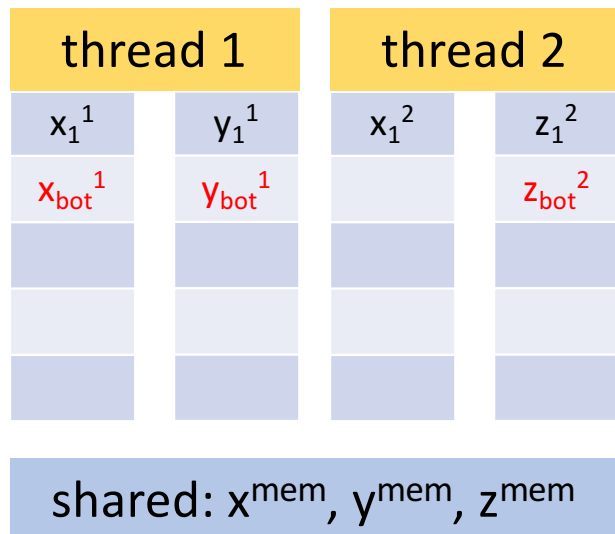
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$$\alpha_{sum} : \mathcal{D} \rightarrow \mathcal{D}^{\natural}$$

Abstraction: handling ∞

- Key insight: summarize and partition.



$$\alpha_{sum} : \mathcal{D} \rightarrow \mathcal{D}^{\natural}$$

Abstraction: handling ∞

- Key insight: summarize and partition.

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x_1^1	y_1^1	x_1^2	z_1^2
x_{bot}^1	y_{bot}^1		z_{bot}^2

shared: $x^{mem}, y^{mem}, z^{mem}$

$$\alpha_{sum} : \mathcal{D} \rightarrow \mathcal{D}^{\natural}$$

∞ solved

cost: loosing precision

$$\gamma_{sum} : \mathcal{D}^{\natural} \rightarrow \mathcal{D}$$

Abstraction: partial buffer state information

$$\mathcal{B}^b \triangleq Var \times Thread \rightarrow \{0; 1; 1+\} \quad (14)$$

$$\delta : \mathcal{S} \rightarrow \mathcal{B}^b \quad (15)$$

$$\delta(S) \triangleq \lambda(x, T). \begin{cases} 0 & \text{if } N_S(x, T) = 0 \\ 1 & \text{if } N_S(x, T) = 1 \\ 1+ & \text{if } N_S(x, T) > 1 \end{cases} \quad (16)$$

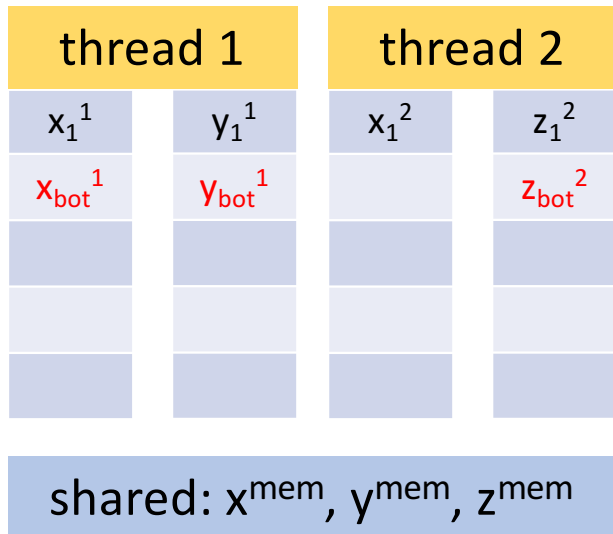


Fig. 5. A partial information on states buffers to partition them

Abstraction: partial buffer state information

$$\gamma_2 : (\mathcal{B}^b \rightarrow \mathcal{D}^{\natural}) \rightarrow (\mathcal{B}^b \rightarrow \mathcal{D}) \quad (22)$$

$$\gamma_2(X^{\sharp}) \triangleq \lambda b^b. \gamma_{sum}(X^{\sharp}(b^b)) \quad (23)$$

$$\gamma : (\mathcal{B}^b \rightarrow \mathcal{D}^{\natural}) \rightarrow \mathcal{D} \quad (24)$$

$$\gamma \triangleq \gamma_1 \circ \gamma_2 = \lambda X^{\sharp}. \{S \in \mathcal{S} \mid S \in \gamma_{sum}(X^{\sharp}(\delta(S)))\} \quad (25)$$

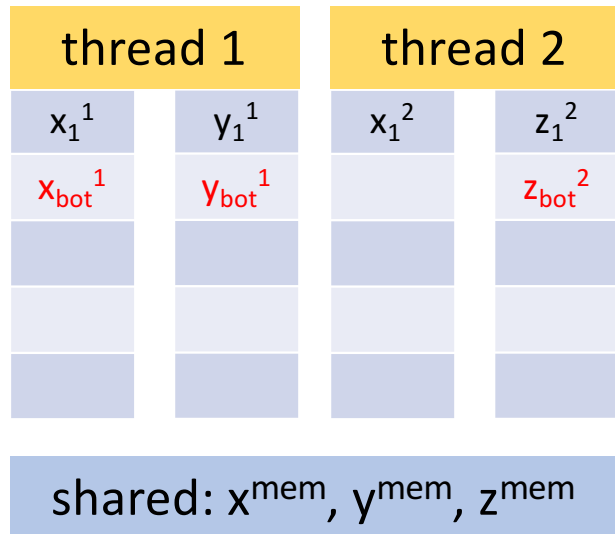


Fig. 8. Summarising the buffers to regain a bounded representation

2 steps:

- 1) summarize
- 2) resolve partition

Abstract transformers

$$\forall T \in \text{Thread}, \{\cdot\}_T : (\mathcal{B}^b \times \mathcal{D}^b) \rightarrow \mathcal{P}(\mathcal{B}^b \times \mathcal{D}^b) \quad (26)$$

$$\{\!|r := x|\!\}_T^\#(b^b, X^b) = \begin{cases} \{b^b, \llbracket r := x^{mem} \rrbracket X^b\} & \text{if } b^b(x^T) = 0 \\ \{b^b, \llbracket r := x_1^T \rrbracket X^b\} & \text{otherwise} \end{cases} \quad (27)$$

$$\{\!|x := e|\!\}_T^\#(b^b, X^b) = \begin{cases} \{b^b[x^T := 1], \llbracket x_1^T := e \rrbracket \circ \llbracket add\ x_1^T \rrbracket X^b\} & \text{if } b^b(x^T) = 0 \\ \{b^b[x^T := 1+], \\ \llbracket x_1^T := e \rrbracket \circ \llbracket x_{bot}^T := x_1^T \rrbracket \circ \llbracket add\ x_{bot}^T \rrbracket X^b\} & \text{if } b^b(x^T) = 1 \\ \{b^b, \llbracket x_1^T := e \rrbracket \circ \llbracket fold\ x_{bot}^T, x_2^{temp} \rrbracket \\ \circ \llbracket x_2^{temp} := x_1^T \rrbracket \circ \llbracket add\ x_2^{temp} \rrbracket X^b\} & \text{if } b^b(x^T) = 1+ \end{cases} \quad (28)$$

$$\{\!|mfence|\!\}_T^\#(b^b, X^b) = \begin{cases} \{b^b, X^b\} & \text{if } \forall x \in \text{Var}, b^b(x^T) = 0 \\ \emptyset & \text{otherwise} \end{cases} \quad (29)$$

$$\{\!|flush\ x|\!\}_T^\#(b^b, X^b) = \begin{cases} \emptyset & \text{if } b^b(x^T) = 0 \\ \{b^b[x^T := 0], \llbracket drop\ x_1^T \rrbracket \circ \llbracket x^{mem} := x_1^T \rrbracket X^b\} & \text{if } b^b(x^T) = 1 \\ \left\{ \begin{array}{l} b^b, \llbracket drop\ x^{temp} \rrbracket \circ \llbracket x^{mem} := x^{temp} \rrbracket \\ \circ \llbracket expand\ x_{bot}^T, x^{temp} \rrbracket X^b; \\ b^b[x^T := 1], \llbracket drop\ x_{bot}^T \rrbracket \circ \llbracket x^{mem} := x_{bot}^T \rrbracket X^b \end{array} \right\} & \text{if } b^b(x^T) = 1+ \end{cases} \quad (30)$$

$$\forall T \in \text{Thread}, \llbracket \cdot \rrbracket_T^\# : (\mathcal{B}^b \rightarrow \mathcal{D}^b) \rightarrow (\mathcal{B}^b \rightarrow \mathcal{D}^b) \quad (31)$$

$$\llbracket ins \rrbracket_T^\# X^\# = \lambda b^b. \bigcup_{\substack{\exists b_1^b \in \mathcal{B}^b, \\ (b^b, X^b) \in \{\!|ins|\!\}_T^\#(b_1^b, X^\#(b_1^b))}} X^b \quad (32)$$

Fig. 9. Abstract semantics with summarisation

Abstract transformers on partitions $\{.\}$

$$\forall T \in \text{Thread}, \{.\} : (\mathcal{B}^b \times \mathcal{D}^q) \rightarrow \mathcal{P}(\mathcal{B}^b \times \mathcal{D}^q)$$

$$\{r := x\}_T^\#(b^b, X^q) = \begin{cases} \{b^b, \llbracket r := x^{mem} \rrbracket X^q\} & \text{if } b^b(x^T) = 0 \\ \{b^b, \llbracket r := x_1^T \rrbracket X^q\} & \text{otherwise} \end{cases} \quad (27)$$

Abstract transformers on partitions $\{.\}$

$$\{x := e\}_T^\#(b^b, X^b) = \begin{cases} \{b^b[x^T := 1], \llbracket x_1^T := e \rrbracket \circ \llbracket add\ x_1^T \rrbracket X^b\} & \text{if } b^b(x^T) = 0 \\ \{b^b[x^T := 1+], \\ \llbracket x_1^T := e \rrbracket \circ \llbracket x_{bot}^T := x_1^T \rrbracket \circ \llbracket add\ x_{bot}^T \rrbracket X^b\} & \text{if } b^b(x^T) = 1 \\ \{b^b, \llbracket x_1^T := e \rrbracket \circ \llbracket fold\ x_{bot}^T, x_2^{temp} \rrbracket \\ \circ \llbracket x_2^{temp} := x_1^T \rrbracket \circ \llbracket add\ x_2^{temp} \rrbracket X^b\} & \text{if } b^b(x^T) = 1+ \end{cases} \quad (28)$$

Abstract transformers $\llbracket \cdot \rrbracket$ using the $\{.\}$

$$\forall T \in \text{Thread}, \llbracket \cdot \rrbracket_T^\# : (\mathcal{B}^b \rightarrow \mathcal{D}^q) \rightarrow (\mathcal{B}^b \rightarrow \mathcal{D}^q)$$

$$\llbracket \text{ins} \rrbracket_T^\# X^\# = \lambda b^b. \bigcup_{\substack{\exists b_1^b \in \mathcal{B}^b, \\ (b^b, X^\#) \in \{\text{ins}\}_T^\#(b_1^b, X^\#(b_1^b))}} X^\#$$

Abstraction: partial buffer state information

$$\gamma_2 : (\mathcal{B}^b \rightarrow \mathcal{D}^{\natural}) \rightarrow (\mathcal{B}^b \rightarrow \mathcal{D}) \quad (22)$$

$$\gamma_2(X^{\sharp}) \triangleq \lambda b^b. \gamma_{sum}(X^{\sharp}(b^b)) \quad (23)$$

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$$\gamma \triangleq \gamma_1 \circ \gamma_2 = \lambda X^{\sharp}. \{S \in \mathcal{S} \mid S \in \gamma_{sum}(X^{\sharp}(\delta(S)))\} \quad (25)$$

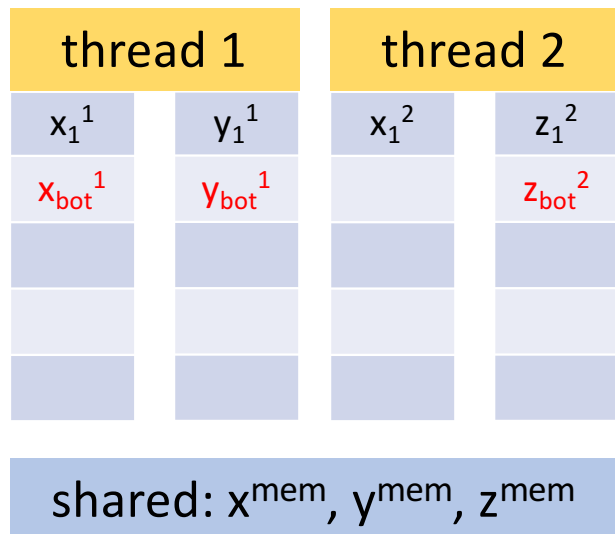


Fig. 8. Summarising the buffers to regain a bounded representation

2 steps:

- 1) summarize
- 2) resolve partition

My own code example

```
// condition to test @ label
{@ (0:end, 1:end) 0:ry0 <= 0:rx0 && 1:ry1 <= 1:rx1 }

// precondition
x0 = 0, y0 = 0, x1 = 0, y1 = 0, rx0 = 0, ry0 = 0, rx1 = 0, ry1 = 0

### thread T0 ###

x0 := 1
y0 := 1
x0 := 2
ry0 := y1
rx0 := x1
label end
```

Result

```
Running test ps_simple
Domain oct, 0 steps before widening
Property 1 could not be verified (wrong, or domain too imprecise).
Time 4.677846
```

```
Running test ps_simple
Domain polka, 0 steps before widening
Property 1 could not be verified (wrong, or domain too imprecise).
Time 0.892813
```

PSO

My own code example with fences

```
// condition to test @ label
{@ (0:end, 1:end) 0:ry0 <= 0:rx0 && 1:ry1 <= 1:rx1 }

// precondition
x0 = 0, y0 = 0, x1 = 0, y1 = 0, rx0 = 0, ry0 = 0, rx1 = 0, ry1 = 0

### thread T0 ###

x0 := 1
mfence
y0 := 1
mfence
x0 := 2
mfence
ry0 := y1
rx0 := x1
label end
```

Result with fences

```
Running test ps_fences  
Domain oct, 0 steps before widening  
Property 1 verified.  
Time 0.203982
```

```
Running test ps_fences  
Domain polka, 0 steps before widening  
Property 1 verified.  
Time 0.050472
```

Code example from paper

```
/* Property to check: At labels (bp0; bp1), tail < h1 */
    int head;

/* ENQUEUE */
int h1;

while true {
    h1 = head;
    bp0:
    h1 = h1 + 1;
    head = h1;
}

/* DEQUEUE */
int tail, h2;

tail = head;
while true {
    h2 = head;
    while (tail >= h2) {
        h2 = head;
    }
    bp1:
    tail = tail + 1;
}
```

```
Running test queue
Domain oct, 1 steps before widening
Property 1 verified.
Time 0.089992
```

Benchmark

Algorithm	Domain	Fences	Time	Mem	Domain	Fences	Time	Mem
Abp	Oct	-	-	-	Bdd+Oct	0	0.3	32
	Poly	-	-	-	Bdd+Poly	0	0.3	32
	AGT	0	6	167				
Bakery	Oct	-	-	-	Bdd+Oct	-	-	-
	Poly	-	-	-	Bdd+Poly	-	-	-
	AGT	4	3429	10951				
Concloop	Oct	2	0.19	38	Bdd+Oct	2	0.29	34
	Poly	2	0.24	37	Bdd+Poly	2	0.29	34
	AGT	2	6	504				
Dekker	Oct	4	23	52	Bdd+Oct	4	62	42
	Poly	4	22	50	Bdd+Poly	4	66	43
	AGT	4	121	1580				
Kessel	Oct	-	-	-	Bdd+Oct	4	4	33
	Poly	-	-	-	Bdd+Poly	4	4	34
	AGT	4	6	198				
Loop2 TLM	Oct	-	-	-	Bdd+Oct	0	4.3	34
	Poly	-	-	-	Bdd+Poly	0	4.2	34
	AGT	2	36	1650				
Peterson	Oct	4	1.53	39	Bdd+Oct	4	2.77	32
	Poly	4	1.53	39	Bdd+Poly	4	2.94	33
	AGT	4	20	901				
Queue	Oct	0	0.15	36.9	Bdd+Oct	0	0.70	34.3
	Poly	1	0.2	34.7	Bdd+Poly	0	0.31	33.3
	AGT	1	1	108				

Fig. 12. Experimental results. Times in sec, Mem in MB.

Benchmark

Algorithm	Domain	Fences	Time	Mem	Domain	Fences	Time	Mem
Abp	Oct	-	-	-	Bdd+Oct	0	0.3	32
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Fig. 12. Experimental results. Times in sec, Mem in MB.

Discussion

- Good things
- Limitations
- Suggested improvements

Acknowledgment

- Thibault Suzanne for the VM with the working analyzer
- Andrei Dan for interesting discussion